Two deformations of a Markov Equation and related topics

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Introduction

In this talk, I will talk about two kinds of deformations of a Markov equation. 1st. kind of deformation (we call it *t*-defrmation) of Markov equation is related to Castling transformation of *t*-dimensional prehomogeneous vector spaces. 2nd.. kind of deformation is related to q-defrmation of rational numbers introduced by Morier-Genoud and Ovsienko, that is connected to knot theory, hyperbolic geometry, Cluster algebra.

What is Local Functional Equation(=LFE) for a pair of polynomials?

§ What is a local functional equation of pair of polynomials.

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What is Local Functional Equation(=LFE) for a pair of polynomials?

Let (P, P^*) be a pair of homogeneous polynomials in *n* variable of degree *d* with real coefficients.

It is interesting problem both in Analysis and in Number Theory to find the following "Local Functional equation"=LFE (avrebiation):

For $\{x \in V | P(x) \neq 0\}_{\mathbb{R}} = \bigcup_{i=1}^{r} \Omega_i$:decomposition to connected components.

$$\widehat{|P(x)|_{i}^{s}}(= \text{Fourier tr. of } |P(x)|_{i}^{s}) = \sum_{j=1}^{\nu} \gamma_{ij}(s) |P^{*}(y)|_{j}^{-\frac{n}{d}-s} \quad (*)$$
$$d = \deg.P = \deg.P^{*}, |P(x)|_{i} := \begin{cases} |P(x)| & (x \in \Omega_{i}) \\ 0 & \text{otherwise} \end{cases}$$

g.P', $|P(x)|_i := \begin{cases} 0 & \text{otherwise} \end{cases}$

where

Remark

$$\widehat{P(x)}|_{i}^{s}(=$$
 Fourier tr. of $|P(x)|_{i}^{s}) = \sum_{j=1}^{\nu} \gamma_{ij}(s) |P^{*}(y)|_{j}^{-\frac{n}{d}-s}$ (*)

 $\begin{array}{l} \partial^{m}f = \frac{\partial^{m_{1}+\cdots+m_{n}}f}{\partial x_{1}^{m_{1}}\cdots\partial x_{n}^{m_{n}}} \text{ for } \forall m = (m_{1},\ldots,m_{n}) \in \mathbb{Z}_{\geq 0}^{n} \\ \varphi \in \mathcal{S}(\mathbb{R}^{n}) := \{f \mid \sup_{x} |Q(x)\partial^{m}f| < \infty \text{ for } \forall \text{polynomial } Q(x)\} \\ \widehat{\varphi}(y) = \int_{\mathbb{R}^{n}} \varphi(x) \exp(2\pi i \langle x, y \rangle) dx : \text{Fourier trans.form of } \varphi \\ \int_{*} |P(x)|^{s} \widehat{\varphi}(x) dx = \sum_{**} (\text{Gamma-factor}) \times \int_{*} |P^{*}(y)|^{-s-\frac{n}{d}} \varphi(y) dy \\ \text{as a distribution} \\ \zeta(\varphi, s) = \int_{*} |P(x)|^{s} \varphi(x) dx : \text{ local zeta function(zeta distribution)} \end{array}$

(*) is also called FE of zeta distribution (local zeta function).

Classical examples

Example 1 : (FT of Positive def. quadratic forms) $(x_1^2 + \cdots + x_n^2)^{s-\frac{n}{2}} = \pi^{-2s+\frac{n}{2}} \Gamma(s) \Gamma(s - \frac{n-2}{2}) (y_1^2 + \cdots + y_n^2)^{-s}$ Example 2 : (FT of Determinant) $|\widehat{\det X|^{s-n}} = (2\pi)^{-ns} (2\pi)^{\frac{n(n-1)}{2}} 2^n \cos(\pi \frac{s}{2}) \cdots \cos(\pi \frac{(s-n+1)}{2}) \times \Gamma(s) \Gamma(s-1) \cdots \Gamma(s-n+1) |\det Y|^{-s}$

For the case of n = 1, this is corresponds to Riemmann zeta function as follows: $\zeta(1-s) = (2\pi)^{-s} \Gamma(s) 2 \cos(\frac{\pi s}{2}) \zeta(s)$

Examples of LFE coming from PV-theory

These examples are coming from relative invarinats of prehomogeneous vector spaces. In simplest case, I will explain local functional equation coming from PV-theory.

Examples of LFE coming from PV-theory

Real PV
$$(GL(1, \mathbb{R}) \times SO(p, q), \Lambda_1, \mathbb{R}_{p,q})$$
 with a relative invariant
 $P^* = P = \sum_{i=1}^{p} x_i^2 - \sum_{j=p+1}^{p+q} x_j^2$ has the following LFEs
(1)If $(p, q) = (n, 0)$,
 $|P|^s = -\pi^{2s+\frac{n}{2}+1}\Gamma(s+1)\Gamma(s+\frac{n}{2})\sin(s\pi)|P|^{-s-\frac{n}{2}}$

Example2 of LFE coming from PV-theory

$$\begin{aligned} (2)(p,q) &= (n-1,1), \\ \left[\begin{array}{c} |\widehat{P}|_{+}^{s} \\ |\widehat{P}|_{-+}^{s} \end{array} \right] &= \pi^{-2s - \frac{p+q}{2} - 1} \Gamma(s+1) \Gamma(s + \frac{p+q}{2}) \\ &\times \begin{bmatrix} -\cos(s\pi) & -\cos(\frac{n\pi}{2}) & -\cos(\frac{n\pi}{2}) \\ \frac{1}{2} & \frac{1}{2} \mathbf{e}[-\frac{2s+n}{4}] & \frac{1}{2} \mathbf{e}[\frac{2s+n}{4}] \\ \frac{1}{2} & \frac{1}{2} \mathbf{e}[\frac{2s+n}{4}] & \frac{1}{2} \mathbf{e}[-\frac{2s+n}{4}] \end{bmatrix} \begin{bmatrix} |P|_{+}^{-s - \frac{p+q}{2}} \\ |P|_{-+}^{-s - \frac{p+q}{2}} \\ |P|_{--}^{-s - \frac{p+q}{2}} \end{bmatrix} \end{aligned}$$

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Example2 of LFE coming from PV-theory

(3) If
$$p, q \ge 2$$
,

$$\begin{bmatrix} |\widehat{P}|_{+}^{s} \\ |\widehat{P}|_{-}^{s} \end{bmatrix} = \pi^{-2s - \frac{p+q}{2} - 1} \Gamma(s+1) \Gamma(s + \frac{p+q}{2})$$

$$\times \begin{bmatrix} -\sin \pi (s + \frac{q}{2}) & \sin(\frac{\pi p}{2}) \\ \sin(\frac{\pi q}{2}) & -\sin \pi (s + \frac{p}{2}) \end{bmatrix} \begin{bmatrix} |P|_{+}^{-s - \frac{p+q}{2}} \\ |P|_{-}^{-s - \frac{p+q}{2}} \end{bmatrix}$$

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Markov equation

Tree of Castling trasnformations of PVs

§ Castling transform of Prehomogeneous vector spaces and *t*-Deformation of Markov triples.

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Tree of Castling trasnformations of PVs

Grassmann duality

$$\wedge^k V \cong (\wedge^{n-k} V)^* \cong \wedge^{n-k} (V^*)$$

The transform coming from this Grassmann duality is called **Castling transform** of vector spaces In particular, Castling transfroms preserve prehomogenety! (Castling transform is introduced by Mikio Sato and Takuro Shintani.)

Tree of Castling trasnformations of PVs

Example

 $(SO(2) \times GL(1) \times GL(1) \times GL(1), \rho \otimes \Lambda_1 \otimes \Lambda_1 \otimes \Lambda_1, V(3) \otimes V(1) \otimes V(1) \otimes V(1)) \leftrightarrow (3, 1, 1, 1)$

 \Rightarrow (castling transform)

 $(SO(2) \times GL(2) \times GL(1) \times GL(1), \rho^* \otimes \Lambda_1 \otimes \Lambda_1 \otimes \Lambda_1, V(3) \otimes V(2) \otimes V(1) \otimes V(1)) \leftrightarrow (3, 2, 1, 1)$

 \Rightarrow (castling transform)

 $(SO(2) \times GL(2) \times GL(5) \times GL(1), \rho \otimes \Lambda_1 \otimes \Lambda_1 \otimes \Lambda_1, V(3) \otimes V(2) \otimes V(5) \otimes V(1)) \leftrightarrow$ (3,2,5,1)

There are two castling transforms for this.

One is $(3, 2, 5, 1) \Rightarrow (3, 13, 5, 1)$ Another is $(3, 2, 5, 1) \Rightarrow (3, 2, 5, 29)$

Tree of Castling trasnformations of PVs

Here we explain the notation:

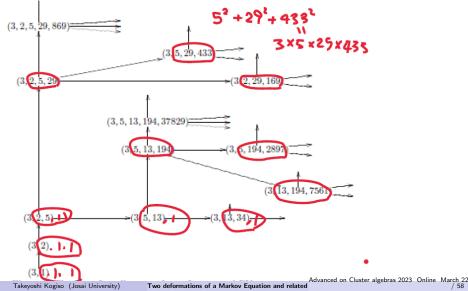
for example, 3-dimensional Prehomogeneous vector space $(SO(3) \times GL(1) \times GL(1) \times GL(1), V(3) \otimes V(1) \otimes V(1) \otimes V(1))$ and $(SL(2) \times GL(1) \times GL(1) \times GL(1), Sym(2) \otimes V(1) \otimes V(1) \otimes V(1))$ corresponds to

(3,1,1,1)

A diagram showing the tree growing from bottom to top with CT is on the next page.

Tree of Castling trasnform. for 3-dim PV and Markov tree

Remark(Markov number and Castling transform of PV)



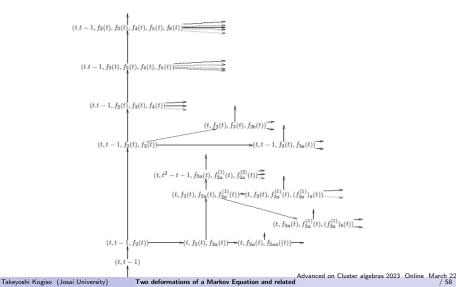
Markov equation

Tree of Castling trasnformations of PVs

For the t-dimensional representation space, the diagram on the next page shows the tree that grows from bottom to top for Castling transformation.

t-Deformations of Markov triples

Castling transform of prehomogeneous vector spaces and t-Deformation of Markov triples



Castling transform of prehomogeneous vector spaces and *t*-Deformation of Markov triples

where

$$\begin{aligned} f_2(t) &= t^2 - t - 1, \\ f_3(t) &= t^4 - 2t^3 + t - 1, \\ f_4(t) &= t^7 - 3t^6 + t^5 + 2t^4 + t^3 - t^2 - t - 1, \\ f_5(t) &= \\ t^{14} - 6t^{13} + 11t^{12} - 2t^{11} - 9t^{10} - 4t^9 + 10t^8 + 7t^7 - 2t^6 - 7t^5 - 3t^4 + t^3 + 2t^2 + t - 1, \\ f_6(t) &= t^{28} - 12t^{27} + 58t^{26} - 136t^{25} + 127t^{24} + 56t^{23} - 126t^{22} - 158t^{21} + \\ 229t^{20} + 196t^{19} - 158t^{18} - 314t^{17} + 34t^{16} + 294t^{15} + 146t^{14} - 142t^{13} - \\ 213t^{12} - 26t^{11} + 116t^{10} + 90t^9 - 9t^8 - 45t^7 - 23t^6 + 5t^5 + 9t^4 + 3t^3 - t^2 - t - 1, \\ f_{3a}(t) &= t^5 - 2t^4 + 2t + 1, t^5 - 2t^4 - t^2 + 2t + 1, \\ f_{2a}^{(1)}(t) &= t^6 - 2t^5 - 2t^4 + 4t^3 - t^2 - t - 1, \\ (f_{2a}^{(1)})_a(t) &= t^9 - 3t^8 - t^7 + 8t^6 - t^5 - 6t^4 - 2t^3 + 3t^2 + 3t - 1, \\ (f_{2a}^{(1)})_b(t) &= t^{10} - 3t^9 - 2t^8 + 11t^7 - t^6 - 12t^5 + 2t^4 + 3t^2 + 1, \\ f_{2a}^{(2)}(t) &= t^{12} - 4t^{11} + 16t^9 - 10t^8 - 22t^7 + 15t^6 + 14t^5 - 5t^4 - 6t^3 + t - 1, \\ f_{3aa}(t) &= t^4 - t^3 - 3t^2 + 2t + 1, \end{aligned}$$

Castling transform of prehomogeneous vector spaces and t-Deformation of Markov triples

In this diagram, Pick up subtree

$$(t, f_{w(a,b)}(t), f_{w(a,b)w'(a,b)}(t), f_{w'(a,b)}(t))$$

starting form

$$(t, f_a(t), f_{ab}(t), f_b(t)) := (t, t^2 - t - 1, t - 1),$$

where Christoffel *ab*-words w(a, b), w(a, b)w'(a, b), w'(a, b) means triplet of *t*-polynomials.

Inother words,

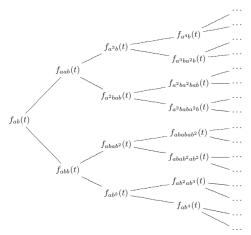
$$(t, f_{w(a,b)}(t), f_{w(a,b)w'(a,b)}(t), f_{w'(a,b)}(t))$$

parametrized by Christoffel *ab*-words.

for example, Castling transform of $(t, f_a(t), f_{ab}(t), f_b(t))$ at $f_{ab}(t)$ is $(t, f_a(t), f_{ab}(t), tf_a(t)f_{ab}(t) - f_b(t))$ and we put $tf_a(t)f_{ab}(t) - f_b(t) = f_{a^2b}(t)$. Thus we can consider a triplet $(f_a(t), f_{a^2b}(t), f_{ab}(t))$ parametrized by Christoffel *ab*-word (a, a^2b, ab) .

Castling transform of prehomogeneous vector spaces and *t*-Deformation of Markov triples

Tree of $\{(f_{w(a,b)}(t), f_{w(a,b)w'(a,b)}(t), f_{w'(a,b)}(t))\}_{(w(a,b),w(a,b)w'(a,b),w'(a,b))\text{is a triple of Christoffel}}\}$



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t-Deformations of Markov triples

Theorem([K, arXiv2008.12913v3])

A triplet $(f_w(t), f_{ww'}(t), f_{w'}(t))$ of polynomials associated to Christoffel *ab*-word triple (w, ww', w'), then $(f_w(t), f_{ww'}(t), f_{w'}(t))$ is a solution of the following equation:

$$x^{2} + y^{2} + z^{2} + (t - 3) = txyz.$$
 (1)

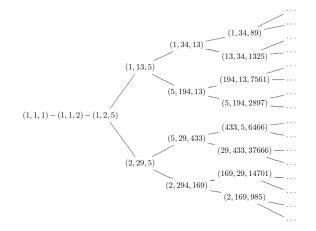
Elementary properties of Markov triples

\S Elementary properties of Markov triples

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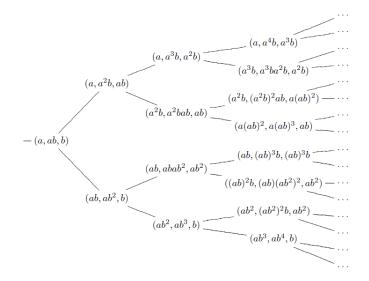
Markov triple, Markov tree

Integer-solution (x, y, z) of equation $x^2 + y^2 + z^2 = 3xyz$ is called Markov triple.



Remark: Markov conjecture: The maxima of each triplet are all different.

Christoffel *ab*-words and Markov triples



Christoffel *ab*-words and Markov triples

Theorem(Cohn cf. [Bombieri], [Aigner])

$$\begin{aligned} A &:= \begin{pmatrix} 2 & 1 \\ 1 & 1 \end{pmatrix}, B &:= \begin{pmatrix} 5 & 2 \\ 2 & 1 \end{pmatrix} \in SL(2, \mathbb{Z}) \\ (w(A, B)_{1,2}, (w(A, B)w'(A, B))_{1,2}, w'(A, B)_{1,2}) &= \\ (\frac{1}{3}\mathrm{tr}(w(A, B)), \frac{1}{3}\mathrm{tr}(w(A, B)w'(A, B)), \frac{1}{3}\mathrm{tr}(w'(A, B))) \\ \text{is a Markov triple for Christoffel } ab-words (w(a, b), w(a, b)w'(a, b), w'(a, b)). \end{aligned}$$

<u>§§</u> Continued fractions and their properties

Well known properties for continued fractions :
For
$$\frac{r}{s} \in \mathbb{Q}$$
, we assume $\frac{r}{s} > 1$ and $gcd(r, s) = 1$,
 $\frac{r}{s} = c_1 - \frac{1}{c_2 - \frac{1}{\cdots - \frac{1}{c_k}}} = a_1 + \frac{1}{a_2 + \frac{1}{\cdots + \frac{1}{a_{2m}}}}$
 $= [[c_1, c_2, \dots, c_k]] = [a_1, a_2, \dots, a_{2m}]$

Example

 $\frac{19}{7} = [2, 1, 2, 2] = [[3, 4, 2]]$

For a regular continued fraction, if $a_n \neq 1$, $[a_1, \ldots, a_{n-1}, a_n] = [a_1, \ldots, a_{n-1}, a_n - 1, 1]$

We can assume n = even = 2mNotations: $N[a_1, \dots, a_{2m}] = [a_1, \dots, a_{2m}]$ -Numerator $D[a_1, \dots, a_{2m}] = [a_1, \dots, a_{2m}]$ -Denominator $N[[c_1, \dots, c_k]] = [[c_1, \dots, c_k]]$ -Numerator $D[[c_1, \dots, c_k]] = [[c_1, \dots, c_k]]$ -Denominator

Theorem1(Euler Continuants, 高木貞治「代数学講義」 or Hardy-Wright) Regular CF and negative CF satisfy the following **Euler's continuants**:

$$N[a_1, \dots, a_{2m}] = \det \begin{pmatrix} a_1 & 1 & & & \\ -1 & a_2 & 1 & & & \\ & -1 & a_3 & 1 & & & \\ & & \ddots & \ddots & \ddots & & \\ & & & -1 & a_{2m-1} & 1 \\ & & & & & -1 & a_{2m} \end{pmatrix}$$

$$N[[c_1, \dots, c_k]] = \det \begin{pmatrix} c_1 & 1 & & & \\ 1 & c_2 & 1 & & & \\ & 1 & c_3 & 1 & & \\ & & \ddots & \ddots & \ddots & \\ & & & 1 & c_{k-1} & 1 \\ & & & & 1 & c_k \end{pmatrix}$$

If $a_1 \neq 0$, $D[a_1, \dots, a_{2m}] = \frac{\partial}{\partial a_1} N[a_1, \dots, a_{2m}]$
If $c_1 \neq 0$, $D[[c_1, \dots, c_k]] = \frac{\partial}{\partial c_1} N[[c_1, \dots, c_k]]$

Theorem2
For
$$\frac{r}{s} \in \mathbb{Q}_{>0}$$
,
 $\frac{r}{s} = [a_1, a_2, \dots, a_{2m}] = [[c_1, c_2, \dots, c_k]]$,
 $M^+(a_1, a_2, \dots, a_{2m}) := \begin{pmatrix} a_1 & 1\\ 1 & 0 \end{pmatrix} \begin{pmatrix} a_2 & 1\\ 1 & 0 \end{pmatrix} \cdots \begin{pmatrix} a_{2m} & 1\\ 1 & 0 \end{pmatrix}$
 $M(c_1, c_2, \dots, c_k) := \begin{pmatrix} c_1 & -1\\ 1 & 0 \end{pmatrix} \begin{pmatrix} c_2 & -1\\ 1 & 0 \end{pmatrix} \cdots \begin{pmatrix} c_k & -1\\ 1 & 0 \end{pmatrix}$
 \Rightarrow

$$M^+(a_1,\ldots,a_{2m}) = \begin{pmatrix} r & r'_{2m-1} \\ s & s'_{2m-1} \end{pmatrix}, M(c_1,\ldots,c_k) = \begin{pmatrix} r & -r_{k-1} \\ s & -s_{k-1} \end{pmatrix}$$

$$\frac{r'_{2m-1}}{s'_{2m-1}} = [a_1,a_2,\ldots,a_{2m-1}], \frac{r_{k-1}}{s_{k-1}} = [[c_1,\ldots,c_{k-1}]]$$

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Corollary of Theorem2

$$R = \begin{pmatrix} 1 & 1 \\ 0 & 1 \end{pmatrix}, \ L = \begin{pmatrix} 1 & 0 \\ 1 & 1 \end{pmatrix}, \ S = \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix},$$

(R, S) and (L, S) is the standard choice of generators of the group $SL(2, \mathbb{Z})$ the above matrices are as follows:

$$M^+(a_1,\ldots,a_{2m})=R^{a_1}L^{a_2}R^{a_3}L^{a_4}\cdots R^{a_{2m-1}}L^{a_{2m}}$$

 $M(c_1,\ldots,c_k)=R^{c_1}SR^{c_2}SR^{c_3}S\cdots R^{c_k}S$

Geometric invariants coming from a graph related to continued fractions

[LS]:K.Lee and R.Schiffler, Cluster algebras and Jones polynomials. Selecta Math. (N.S.) 25 (2019), no. 4, Paper No. 58, 41 pp. [KW]:T.Kogiso, and M. Wakui, A bridge between Conway-Coxeter friezes and rational tangles through the Kauffman bracket polynomials. J. Knot Theory Ramifications 28 (2019), no. 14, 1950083, 40 pp. [NT]:W.Nagai and Y.Terashima, Cluster variables, ancestral triangles and Alexander polynomials, Adv. Math. 363 (2020), 106965, 37 pp. [MO]:S. Morier-Genoud, V. Ovsienko, q-deformed rationals and q-continued fractions, Forum Math. Sigma 8 (2020), No.e13, 55pp.

 $[LS] \Rightarrow$ Jones polynomials of 2-bridge links by using Snake graph and F-polynomials.

 $[KW] \Rightarrow$ Kauffman bracket polynomials of 2-bridge links by using Ancestral triangles and Conway-Coxeter frieze.

 $[NT] \Rightarrow$ Alexander polynomials and Jones polynomials of 2-bridge links by using Ancestral triangles and *F*-Polynomials.

 $[MO] \Rightarrow$ Jones polynomials of 2-bridge links by using Fraey Boats.

q-deformation q-Analogue of continued fractions

q-Continued fractions and their properties

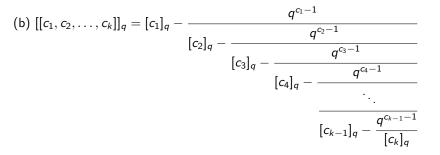
§§ *q*-Deformations of continued fractions

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Sophie Morier-Genord and Valentin Ovsienko, *q*-deformed rationals and *q*-continued fractions, Forum Math. Sigma 8 (2020), Paper No. e13, 55 pp.

Definition 1.1 (a) $[a_1, a_2, \dots, a_{2m}]_q := [a_1]_q + \frac{q^{a_1}}{[a_2]_{q^{-1}} + \frac{q^{-a_2}}{[a_3]_q + \frac{q^{a_3}}{[a_4]_{q^{-1}} + \frac{q^{-a_4}}{\vdots}}}$ $[a_4]_{q^{-1}} + \frac{q^{-a_4}}{[a_{2m-1}]_q + \frac{q^{a_{2m-1}}}{[a_{2m}]_{q^{-1}}}}$



Theorem 1(M-J and O)

$$\frac{r}{s} = [a_1, \dots, a_{2m}] = [[c_1, \dots, c_k]]$$

$$\Rightarrow$$

$$[a_1, \dots, a_{2m}]_q = [[c_1, \dots, c_k]]_q$$
then $[a_1, \dots, a_{2m}]_q = [[c_1, \dots, c_k]]_q =: [\frac{r}{s}]_q$

Example

$$\begin{split} [\frac{5}{2}]_{q} &= [[3,2]]_{q} = [2,2]_{q} = \frac{1+2q+q^{2}+q^{3}}{1+q} \\ [\frac{5}{3}]_{q} &= [[2,3]]_{q} = [1,1,1,1]_{q} = \frac{1+q+2q^{2}+q^{3}}{1+q+q^{2}} \\ [\frac{7}{3}]_{q} &= [[3,2,2]]_{q} = [2,3]_{q} = \frac{1+2q+2q^{2}+q^{3}+q^{4}}{1+q+q^{2}} \\ [\frac{7}{4}]_{q} &= [[2,4]]_{q} = [1,1,2,1]_{q} = \frac{1+q+2q^{2}+2q^{3}+q^{4}}{1+q+q^{2}+q^{3}} \\ [\frac{7}{5}]_{q} &= [[2,2,3]]_{q} = [1,1,2,1]_{q} = \frac{1+q+2q^{2}+2q^{3}+q^{4}}{1+q+2q^{2}+q^{3}} \\ [for the case of denominator [2]_{q}, \\ (c)[\frac{2m+1}{2}]_{q} &= \frac{1+2q+2q^{2}+\dots+2q^{m-1}+q^{m}+q^{m+1}}{1+q} \\ (d)[\frac{3m+1}{3}]_{q} &= \frac{1+2q+3q^{2}+3q^{3}+\dots+3q^{m-1}+2q^{m}+q^{m+1}+q^{m+2}}{1+q+q^{2}} \\ [\frac{3m+2}{2}]_{a} &= \frac{1+2q+3q^{2}+3q^{3}+\dots+3q^{m-1}+2q^{m}+q^{m+1}+q^{m+2}}{1+q+q^{2}} \\ Takeyoshi Kogiso (Josai University) Two deformations of a Markov Equation and related Advanced on Cluster algebras 2023. Online March 222 \\ / 58 \end{split}$$

Theorem (Morier-Genoud and V.Ovsienko, 2019) $M^+(a_1, a_2, b_2)$

$$\begin{array}{c} \left(\begin{bmatrix} a_1 \end{bmatrix}_q & q^{a_1} \\ 1 & 0 \end{array} \right) \left(\begin{bmatrix} a_2 \end{bmatrix}_{q^{-1}} & q^{-a_2} \\ 1 & 0 \end{array} \right) \cdots \left(\begin{bmatrix} a_{2m-1} \end{bmatrix}_q & q^{a_{2m-1}} \\ 1 & 0 \end{array} \right) \left(\begin{bmatrix} a_{2m} \end{bmatrix}_{q^{-1}} & -q^{-a_{2m}} \\ 1 & 0 \end{array} \right) \\ \begin{array}{c} M_q(c_1, \dots, c_k) := \\ \left(\begin{bmatrix} c_1 \end{bmatrix}_q & -q^{c_1-1} \\ 1 & 0 \end{array} \right) \left(\begin{bmatrix} c_2 \end{bmatrix}_q & -q^{c_2-1} \\ 1 & 0 \end{array} \right) \cdots \left(\begin{bmatrix} c_{k-1} \end{bmatrix}_q & -q^{c_{k-1}-1} \\ 1 & 0 \end{array} \right) \left(\begin{bmatrix} c_k \end{bmatrix}_q & -q^{c_k-1} \\ 1 & 0 \end{array} \right) \\ \Rightarrow$$

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(i)
$$M_q^+(a_1, \ldots, a_{2m}) = \begin{pmatrix} q\mathcal{R} & \mathcal{R}'_{2m-1} \\ q\mathcal{S} & \mathcal{S}'_{2m-1} \end{pmatrix}$$

where $\frac{\mathcal{R}(q)}{\mathcal{S}(q)} = [a_1, a_2, \ldots, a_{2m}]_q, \quad \frac{\mathcal{R}'_{2m-1}(q)}{\mathcal{S}'_{2m-1}(q)} = [a_1, \ldots, a_{2m-1}]_q$
(ii) $M_q(c_1, \ldots, c_k) = \begin{pmatrix} \mathcal{R} & -q^{c_k-1}\mathcal{R}_{k-1} \\ \mathcal{S} & -q^{c_k-1}\mathcal{S}'_{k-1} \end{pmatrix}$
where $\frac{\mathcal{R}(q)}{\mathcal{S}(q)} = [[c_1, \ldots, c_k]]_q, \quad \frac{\mathcal{R}_{k-1}(q)}{\mathcal{S}_{k-1}(q)} = [c_1, \ldots, c_{k-1}]_q$
(iii) $R_q := \begin{pmatrix} q & 1 \\ 0 & 1 \end{pmatrix}, \quad L_q := \begin{pmatrix} 1 & 0 \\ 1 & q^{-1} \end{pmatrix}, \quad S_q := \begin{pmatrix} 0 & -q^{-1} \\ 1 & 0 \end{pmatrix}$
 \Rightarrow
 $M_q^+(a_1, \ldots, a_{2m}) = R_q^{a_1}L_q^{a_2} \cdots R_q^{a_{2m-1}}L_q^{a_{2m}}$
 $M_q^+(c_1, \ldots, c_k) = R_q^{c_1}S_qR_q^{c_2}S_q \cdots S_qR_q^{c_k}S_q$

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$$\begin{split} M_{q}^{+}(a_{1},\ldots,a_{2m}) &= \begin{pmatrix} K_{2m}^{+}(a_{1},\ldots,a_{2m})_{q} & q^{a_{2m}}K_{2m-1}^{+}(a_{1},\ldots,a_{2m-1})_{q^{-1}} \\ K_{2m-1}^{+}(a_{2},\ldots,a_{2m})_{q} & q^{a_{2m}}K_{2m-2}^{+}(a_{2},\ldots,a_{2m-1})_{q^{-1}} \end{pmatrix} \\ M_{q}(c_{1},\ldots,c_{k}) &= \begin{pmatrix} K_{k}(c_{1},\ldots,c_{k})_{q} & -q^{c_{k}-1}K_{k-1}(c_{1},\ldots,c_{k-1})_{q} \\ K_{k-1}(c_{2},\ldots,c_{k})_{q} & -q^{c_{k}-1}K_{k-2}(c_{2},\ldots,c_{k-1})_{q} \end{pmatrix} \\ (v) \text{ For } [\frac{r}{s}]_{q} &= [a_{1},a_{2},\ldots,a_{2m}]_{q} = [[c_{1},\ldots,c_{k}]]_{q} &= \frac{\mathcal{R}(q)}{\mathcal{S}(q)}, \\ \mathcal{R}(q) &= K_{k}(c_{1},\ldots,c_{k})_{q} &= q^{a_{2}+a_{4}+\cdots+a_{2m-1}}K_{2m}^{+}(a_{1},a_{2},\ldots,a_{2m})_{q} \\ \mathcal{S}(q) &= K_{k-1}(c_{1},\ldots,c_{k})_{q} &= q^{a_{2}+a_{4}+\cdots+a_{2m}-1}K_{2m-1}^{+}(a_{2},\ldots,a_{2m})_{q} \\ (vi) K_{k}(c_{1},\ldots,c_{k})_{q} &= q^{c_{1}+c_{2}+\cdots+c_{c}-k}K_{k}(c_{k},\ldots,c_{1})_{q^{-1}} \end{split}$$

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(vii) If
$$(c_1, \ldots, c_k)$$
 is quiddity sequence of a triangulated *n*-gon one has
 $K_k(c_1, \ldots, c_k)_q = K_{n-k-2}(c_{k+2}, \ldots, c_n)_q$
(viii) (*q*-Ptolemy relation)
 $K_{i,j}^q := K_{j-i-1}(c_{i+1}, \ldots, c_{j-1})_q$ ($K_{i,i}^q = 0, K_{i,i+1}^q = 1$)
 \Rightarrow
 $K_{i,j}^q K_{j,\ell}^q = q^{c_j + \cdots + c_{k-1} - (k-j)} K_{i,j}^1 K_{k,\ell}^q + K_{j,k}^q K_{i,\ell}^q$ ($1 \le i < j < k < \ell \le n$)
(Ptolemy-relation)

$$\begin{split} \mathbf{Example} \\ \frac{5}{3} &= 1 + \frac{2}{3} = 1 + \frac{1}{1 + \frac{1}{2}} = [1, 1, 2] = [1, 1, 1, 1] = 1 - \frac{1}{3} = [[2, 3]] \\ \text{and} \\ (i) M_q(2, 3) &= \begin{pmatrix} [2]_q & -q^{2-1} \\ 1 & 0 \end{pmatrix} \begin{pmatrix} [3]_q & -q^{3-1} \\ 1 & 0 \end{pmatrix} = \begin{pmatrix} \mathcal{R} & -q^2 \mathcal{R}'_{k-1} \\ \mathcal{S} & -q^2 \mathcal{S}'_{k-1} \end{pmatrix} \\ M_q^+(1, 1, 1, 1) &= \begin{pmatrix} [1]_q & q \\ 1 & 0 \end{pmatrix} \begin{pmatrix} [1]_{q^{-1}} & q^{-1} \\ 1 & 0 \end{pmatrix} \begin{pmatrix} [1]_q & q \\ 1 & 0 \end{pmatrix} \begin{pmatrix} [1]_{q^{-1}} & q^{-1} \\ 1 & 0 \end{pmatrix} = \\ \begin{pmatrix} q^{-1} \mathcal{R} & q^{-2} \mathcal{R}_{2m-1} \\ q^{-1} \mathcal{S} & q^{-2} \mathcal{S}_{2m-1} \end{pmatrix} \\ \frac{M_q(2, 3)(1, 1)}{M_q(2, 3)(2, 1)} &= \frac{1 + q + 2q^2 + q^3}{1 + q + q^2} = \frac{M_q^+(1, 1, 1, 1)(1, 1)}{M_q^-(1, 1, 1, 1)(2, 1)} \end{split}$$

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$$\begin{aligned} R_{q}L_{q}R_{q}L_{q} &= \begin{pmatrix} q & 1 \\ 0 & 1 \end{pmatrix} \begin{pmatrix} 1 & 0 \\ 1 & q^{-1} \end{pmatrix} \begin{pmatrix} q & 1 \\ 0 & 1 \end{pmatrix} \begin{pmatrix} 1 & 0 \\ 1 & q^{-1} \end{pmatrix} \\ R_{q}^{2}S_{q}R_{q}^{3}S_{q} &= \begin{pmatrix} q & 1 \\ 0 & 1 \end{pmatrix}^{2} \begin{pmatrix} 0 & q^{-1} \\ 1 & 0 \end{pmatrix} \begin{pmatrix} q & 1 \\ 0 & 1 \end{pmatrix}^{3} \begin{pmatrix} 0 & -q^{-1} \\ 1 & 0 \end{pmatrix} = M_{q}(3,2) = \\ \begin{pmatrix} [2]_{q} & -q^{2-1} \\ 1 & 0 \end{pmatrix} \begin{pmatrix} [3]_{q} & -q^{3-1} \\ 1 & 0 \end{pmatrix} \\ \det \begin{pmatrix} [2]_{q} & q^{2-1} \\ 1 & [3]_{q} \end{pmatrix} &= [2]_{q}[3]_{q} - q = N[\frac{3}{2}]_{q} = q^{3} \det \begin{pmatrix} [1]_{q} & q \\ -1 & [1]_{q^{-1}} & q^{-1} \\ -1 & [1]_{q} & q \\ -1 & [1]_{q^{-1}} \end{pmatrix} \end{aligned}$$

$$\begin{split} & [\frac{5}{3}]_q = [1, 1, 1, 1]_q = [[2, 3]]_q = \frac{\mathcal{R}(q)}{\mathcal{S}(q)} \\ & \mathcal{R}(q) = \mathcal{K}_k(c_1, \dots, c_k) = q^{a_2 + \dots a_{2n} - 1} \mathcal{K}_{2m}^+(a_1, \dots, a_{2m})_q \\ & \mathcal{S}(q) = \mathcal{K}_{k-1}(c_2, \dots, c_k) = q^{a_2 + \dots a_{2n} - 1} \mathcal{K}_{2m-1}^+(a_2, \dots, a_{2m})_q \end{split}$$

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Takeyoshi Kogiso (Josai University)

q-Deformation of Markov triples and Markov equations

§ *q*-Deformation of Markov triples and Markov equations

q-Deformations of Markov triples

Theorem1([K], arXiv2008.12913v3)
Put
$$A_q := \begin{pmatrix} q+1 & q^{-1} \\ 1 & q^{-1} \end{pmatrix}$$
, $B_q := \begin{pmatrix} \frac{q^3+q^2+2q+1}{q} & \frac{q+1}{q^2} \\ \frac{q+1}{q} & q^{-2} \end{pmatrix} \in SL(2, \mathbb{Z}[q, q^{-1}])$,
 \Rightarrow
 $(x, y, z) =$
 $(\operatorname{trw}(A_q, B_q)/[3]_q, \{\operatorname{trw}(A_q, B_q)w'(A_q, B_q)\}/[3]_q, \operatorname{tr}(w'(A_q, B_q)/[3]_q) \in \mathbb{Z}[q, q^{-1}]^3$
is a solution of

$$x^{2} + y^{2} + z^{2} + \frac{(q-1)^{2}}{q^{3}} = [3]_{q}xyz$$

for a Christoffel *ab*-words (w(a, b), w(a, b)w'(a, b), w'(a, b)).

q-Deformations of Markov triples

Theorem2([K], arXiv2008.12913v3.) If $(x, y, z) = (a_q, b_q, c_q)$ is a solution of (**q) $x^2 + y^2 + z^2 + \frac{(q-1)^2}{q^3} = [3]_q xyz$ \Rightarrow $(\tilde{x}, y, z) = ([3]_q b_q c_q - a_q, b_q, c_q), (x, \tilde{y}, z) = (a_q, [3]_q a_q c_q - b_q, c_q), (x, y, \tilde{z}) =$ $(a_q, b_q, [3]_q a_q b_q - c_q)$ is also a solution of (**q).

q-Deformations of Markov triples

$$\begin{aligned} & \mathsf{Example1} \\ & \left(\frac{\operatorname{tr}(A_q^3 B_q)}{[3]_q}\right)^2 + \left(\frac{\operatorname{tr}(A_q^3 B_q A_q^2 B_q)}{[3]_q}\right)^2 + \left(\frac{\operatorname{tr}(A_q^2 B_q)}{[3]_q}\right)^2 + \frac{(q-1)^2}{q^3} \\ &= \left\{\frac{(q^2+1)(q^6+3 q^5+3 q^4+3 q^3+3 q^2+3 q+1)}{q^5}\right\}^2 + \\ & \left\{\frac{(q^4+q^3+q^2+q+1)(q^{12}+5 q^{11}+12 q^{10}+22 q^9+32 q^8+39 q^7+43 q^6+39 q^5+32 q^4+22 q^3+12 q^2+5 q+1)}{q^9}\right\}^2 + \\ & \left\{\frac{q^4+q^3+q^2+q+1}{q^3}\right\}^2 + \frac{(q-1)^2}{q^3} \\ &= [3]_q \left\{\frac{(q^2+1)(q^6+3 q^5+3 q^4+3 q^3+3 q^2+3 q+1)}{q^5}\right\} \\ & \left\{\frac{(q^4+q^3+q^2+q+1)(q^{12}+5 q^{11}+12 q^{10}+22 q^9+32 q^8+39 q^7+43 q^6+39 q^5+32 q^4+22 q^3+12 q^2+5 q+1)}{q^9}\right\} \\ & \left\{\frac{q^4+q^3+q^2+q+1}{q^3}\right\} \\ &= [3]_q \frac{\operatorname{tr}(A_q^3 B_q)}{[3]_q} \frac{\operatorname{tr}(A_q^3 B_q A_q^2 B_q)}{[3]_q} \frac{\operatorname{tr}(A_q^2 B_q)}{[3]_q} \end{aligned}$$

Takeyoshi Kogiso (Josai University)

Castling transform and t-Deformations of Markov triples

Tree of $(\{(f_{w(a,b)}(t), f_{w(a,b)w'(a,b)}(t), f_{w'(a,b)}(t))\}_{(w(a,b),w(a,b)w'(a,b),w'(a,b))$ is a triple of Christoffel

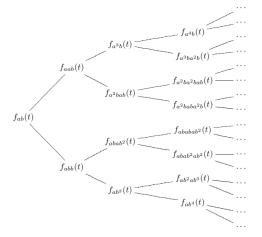


Figure:

Two deformations of a Markov Equation and related

t-Deformations of Markov triples

Theorem([K], arXiv2008.12913v3) For Christoffel *ab*-word triple (w, ww', w'), $(f_w(t), f_{ww'}(t), f_{w'}(t))$ is a solution of

$$x^{2} + y^{2} + z^{2} + (t - 3) = txyz.$$
 (2)

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Relation of q-Deformations and t-Deformations

Theorem([K], arXiv2008.12913v3)

(i)For *t*-deformation $f_w(t)$ and *q*-deformation of Markov number associated with christoffel *ab*-word *w*,

 \Rightarrow

$$f_w([3]_q/q) = qh_w(q).$$
 (3)

(ii) There exists one to one correpondence between the set of q-deformation of a Markov triple and t-deformation of the Markov triple.

(iii) For the value q such that $A_q B_q = B_q A_q$ namely q = -1 or $q = e^{\pm \frac{2}{3}\pi\sqrt{-1}}$ \Rightarrow $x^2 + y^2 + z^2 - 4 = xyz$ (Zagier type).

Relation of q-Deformations and t-Deformation

Example

$$\begin{aligned} (i)f_{a^{2}b}(q^{-1}[3]_{q}) &= q^{-3}[3]_{q}^{3} - q^{-2}[3]_{q}^{2} - 2q^{-1}[3]_{q} + 1 \\ &= q^{-3}\{q^{6} + 2q^{5} + 2q^{4} + 3q^{3} + 2q^{2} + 2q + 1\} \\ &= qh_{a^{2}b}(q) \end{aligned}$$

$$\begin{aligned} &(\text{ii})qh_{a^{2}bab}(q) = \\ &q^{-6}(q^{12}+4q^{11}+9q^{10}+16q^{9}+23q^{8}+29q^{7}+30q^{6}+29q^{5}+23q^{4}+16q^{3}+9q^{2}+4q+1) \\ &= (q^{-1}[3]_{q})^{6}-2(q^{-1}[3]_{q})^{5}-2(q^{-1}[3]_{q})^{4}+4(q^{-1}[3]_{q})^{3}+(q^{-1}[3]_{q})^{2}-(q^{-1}[3]_{q})-1 \\ &= t^{6}-2t^{5}-2t^{4}+4t^{3}+t^{2}-t-1 \\ &= f_{a^{2}bab}(t). \end{aligned}$$

Future Problems

Classify and charaterize prehomogeneous vector spaces coming from F-polynomials associated to quivers of type A.

Future Problems

Thanks

Thank you for your attention!

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